



Digitalization and Maritime Autonomous Surface Ships (MASS)



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INTERNATIONAL, NATIONAL REGULATION

ITALIAN COAST GUARD HEADQUARTERS



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6° Reparto- Sicurezza della navigazione

AGENDA

1. Introduction
2. Autonomous ships in the world...Why?
3. Cost-benefit
4. Implication for international maritime law



1. Introduction

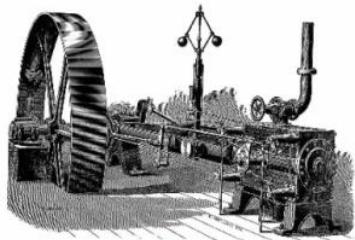
- IMO Maritime Safety Committee's 99th session (May 2018) undertook first consideration of a scoping exercise for MASS (target 2020)



- Are MASS a potential game-changer in shipping, and if so, in what respect?



The fourth shipping revolution is on



1800



1900



1970



2010



1. Mechanized Power



2. Mass Production



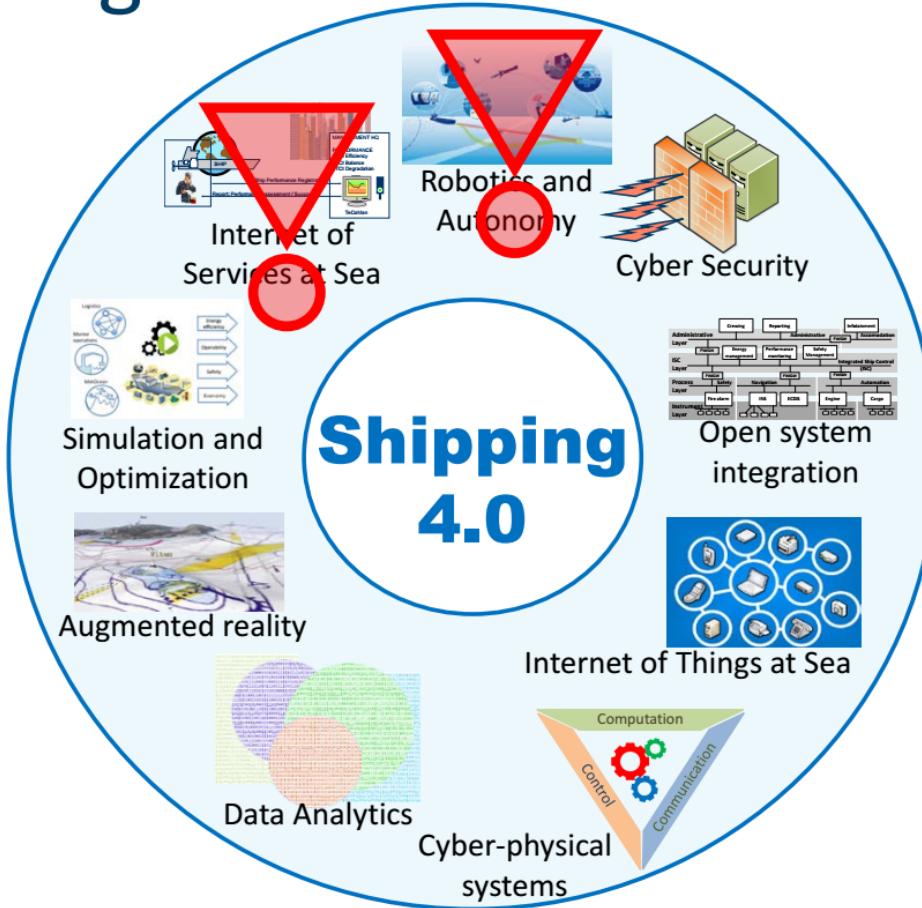
3. Computerized Control



4. Shipping 4.0



Shipping 4.0

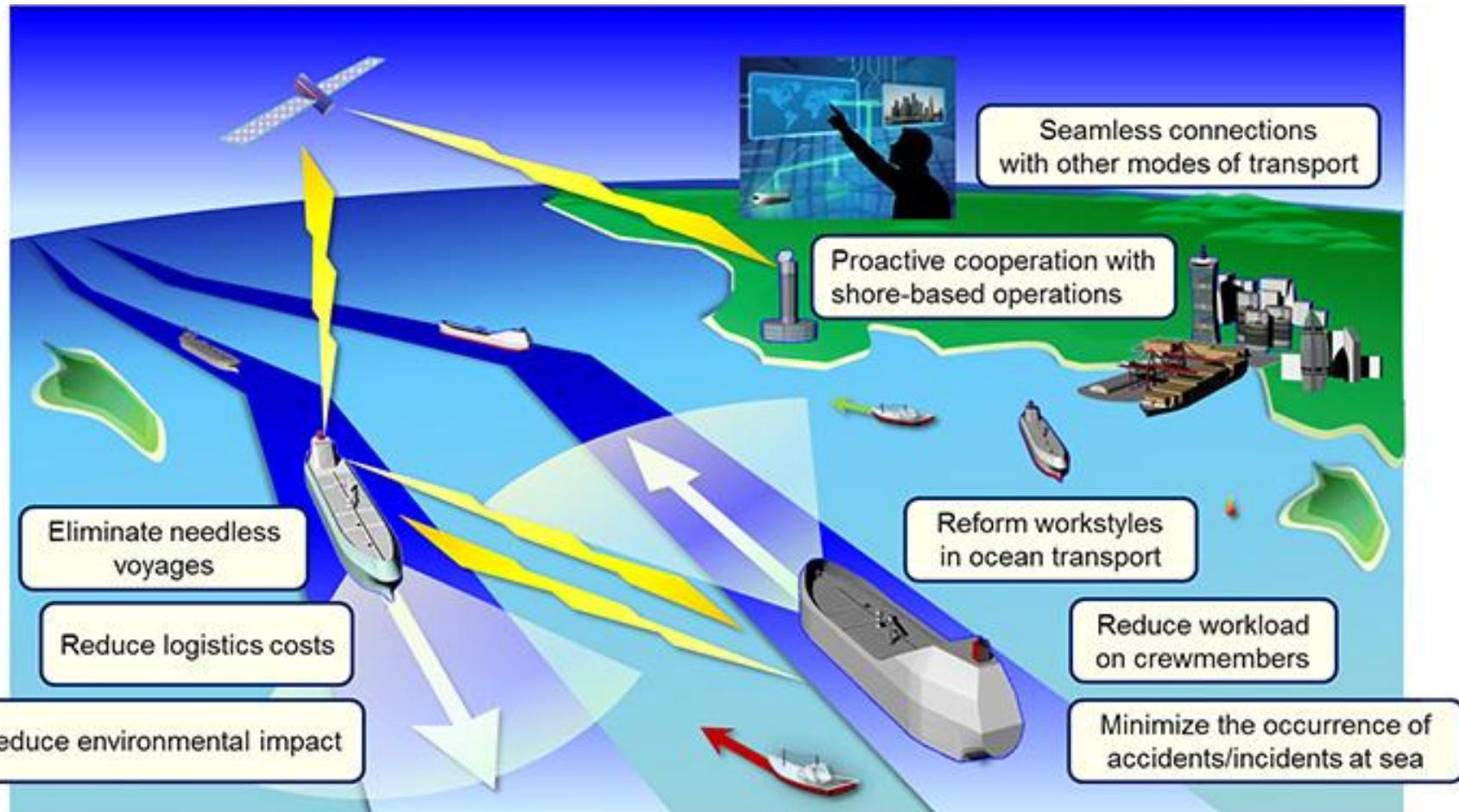


Possible **game changers** in
Shipping 4.0:

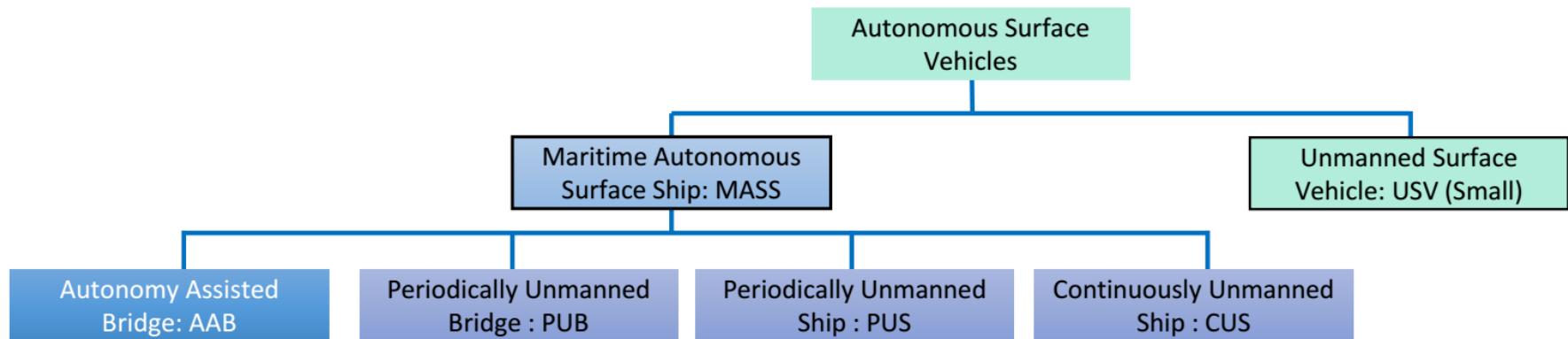
- Digitalization of commercial shipping processes
- Autonomous and unmanned ships



2. Autonomous ships in the world...Why?



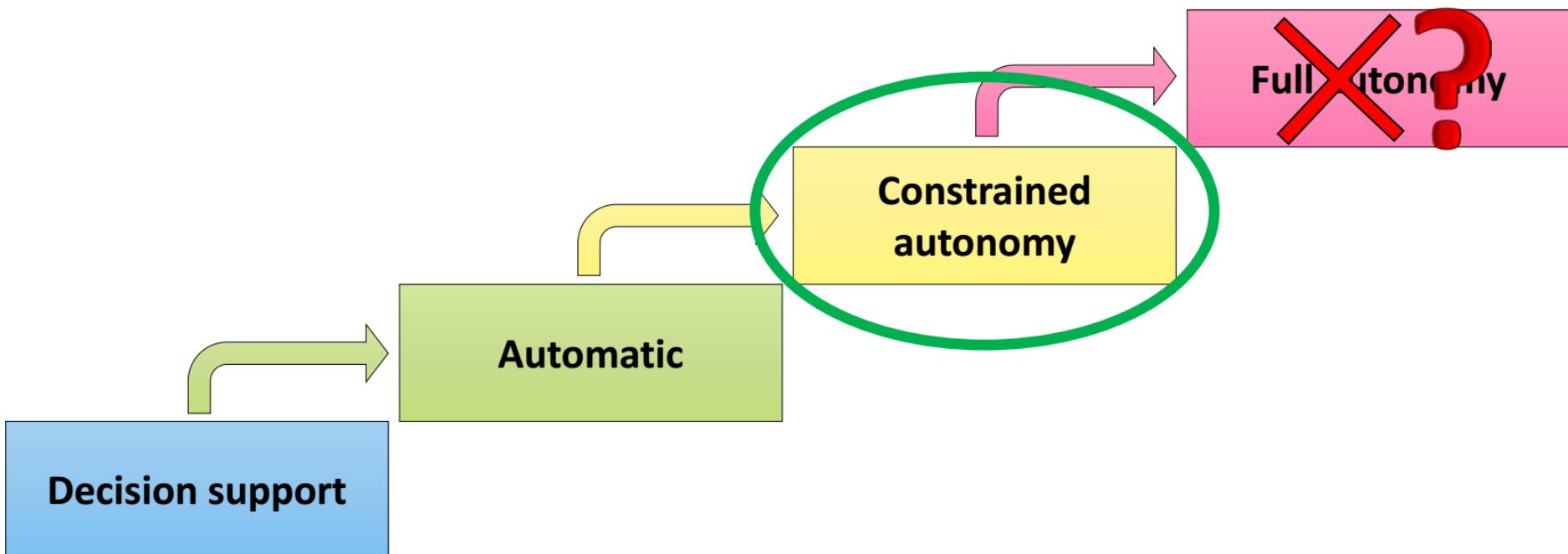
Types of autonomous ships – manning levels



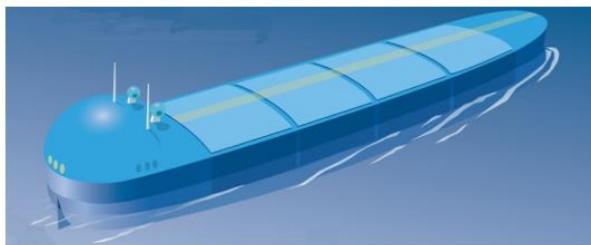
Ship type	Always on Bridge	Available on Ship	Never on Bridge
AAB	x		
PUB		x	
PUS			x
CUS			x



Operational autonomy levels



Completely unmanned gives largest benefits!



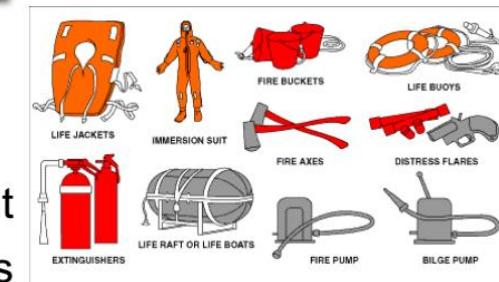
No accommodation
Less power
More cargo



No crew
No crew related costs



Enables completely new
ship concepts



No safety equipment
New constructions

NCE Maritime Clean Tech & NCL

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No maintenance on board

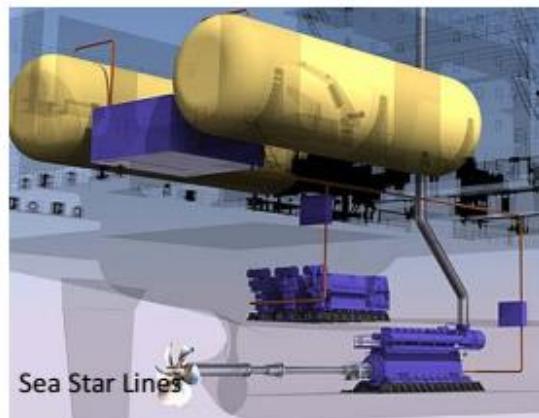


Redundancy



Minimize systems onboard

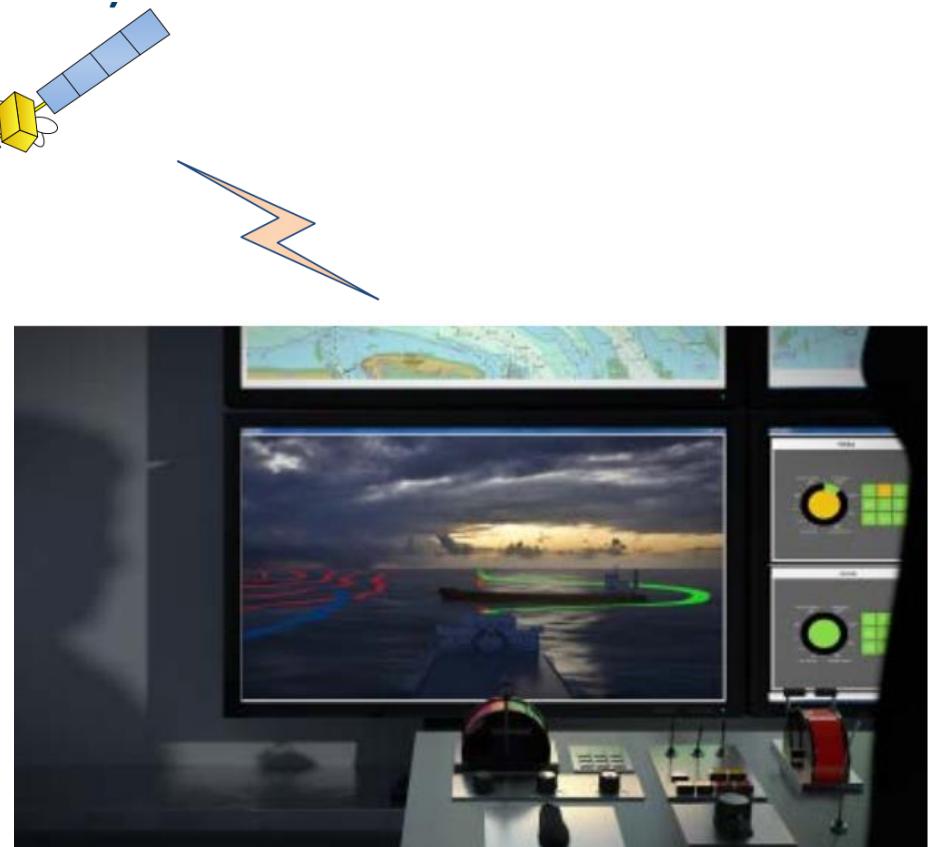
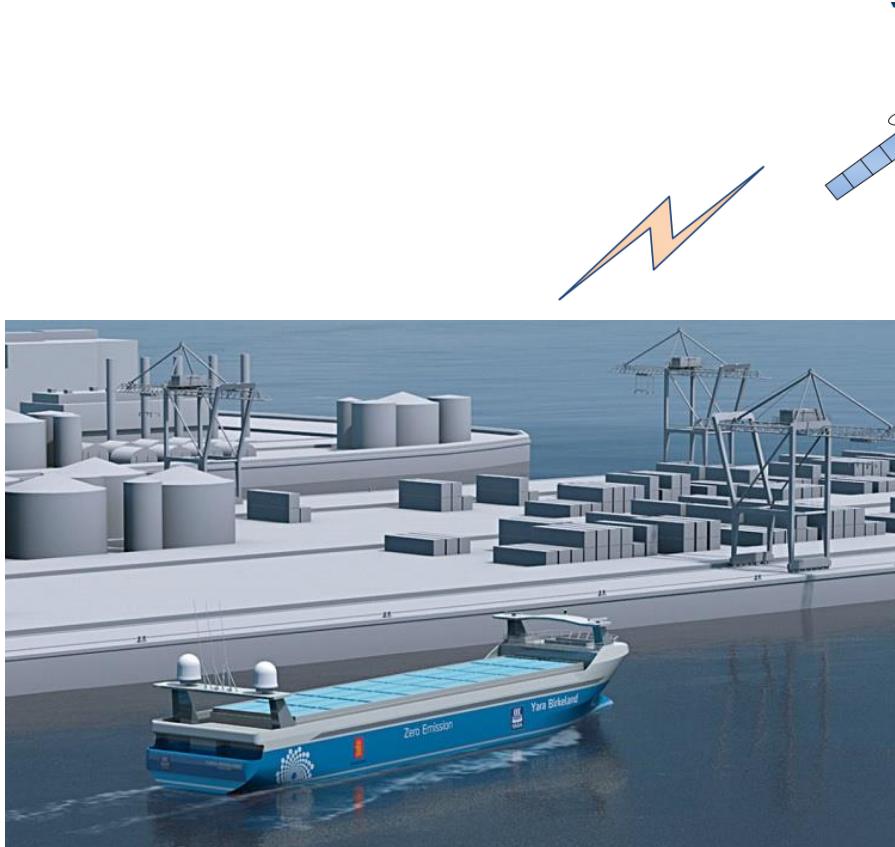
No heavy fuel oil



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A shore Control Centre (SCC) is normally needed



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Why not unmanned ships?

Omission of accomodations and hotellery systems

- Reduced material and production costs
- Reduced light ship weight, wind resistance and fuel consumption

Autonomous navigation technology

- Advanced Sensor Module
- Deep Sea Navigation System

Technical system redundancy

- Sensors and electronics
- Communications
- Machinery

Engine room and propulsion

- Two main engines
- Twin skeg hull
- Additional fuel efficiency gains possible



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3. Cost-benefit

- No hotel
- No crew
- Improved efficiency
- Less off-hire
- New business model



- Dual propulsion, no HFO
- Shore Control Centre
- Longer dockings
- Costlier instruments
- Existing business model



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Legal and liability issues



- Contracts

- UNCLOS
- SOLAS



Easier to do this in national waters.

- Insurance
- Liability



4. Implications for International Maritime law

- Maritime conventions are largely premised on a human presence on board (design of ship as a safe work space, control of the navigation of the ship, provision of notices, log book entries, reporting, pilotage services, responding to distress)

Maritime Safety

- Operations (SOLAS)
- Design, construction, equipping (SOLAS, Load Lines Convention)

Crew training, certification and work conditions (STCW)

- Expectation
- Sufficient manning
- Flexibility
- Watch requirement
- Redundancies



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Rules of the road (COLREGS)

Environment protection

Maritime security



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MARITIME SAFETY COMMITTEE
100th session
Agenda item 5

MSC 100/5/X
28 September 2018
Original: ENGLISH

REGULATORY SCOPING EXERCISE FOR THE USE OF MARITIME AUTONOMOUS SURFACE SHIPS (MASS)

Report of the Correspondence Group

Submitted by Finland

SUMMARY

Executive summary: This document reports on the outcome of the Correspondence Group on a regulatory scoping exercise for the use of Maritime Autonomous Surface Ships (MASS) established at MSC 99

Strategic direction: 2

Output: 2.7

Action to be taken: Paragraph 8

Related documents: MSC 99/22, MSC 99/WP.9;

Introduction



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Appendix 1

Template for the regulatory scoping exercise

Instrument: [Name of instrument]

Provision	Degree of autonomy	MASS application (.A, .B, .C, D)	Clarify, Amend or Gap (For option C only)	First step	Second step
				Comments/Remarks (explain analysis conducted in determining "MASS application")	Possible-The most appropriate way of addressing MASS operations (.I, .II, .III, .IV)
	.1				
	.2				
	.3				
	.4				
	.1				
	.2				
	.3				
	.4				

References:

Degrees of autonomy:

- .1 Ship with automated processes and decision support
- .2 Remotely controlled ship with seafarers on board
- .3 Remotely controlled ship without seafarers on board
- .4 Fully autonomous ship

MASS application:

- .4 A apply to MASS and preclude prevent MASS operations; or
- .2 B apply to MASS and do not preclude prevent MASS operations and require no actions; or
- .3 C apply to MASS and do not preclude prevent MASS operations but may need to be amended or clarified, and/or may contain gaps; or
- .4 D have no application to MASS operations.

The most appropriate way of addressing MASS operations:

- .1 I equivalences as provided for by the instruments or developing interpretations; and/or
- .2 II amending existing instruments; and/or
- .3 III developing new instruments; or



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